Homework 8: Gradient descent

Hand in: 09.12.2025 (Tuesday)

Please follow the submission instructions from the webpage of the course.

Correction: tutorial session on 11.12.2025 (Thursday)

Exercise 1: Gradient descent on overparameterized linear least squares problems (10 points)

This exercise is inspired from Exercise 7 in Chapter 3 of the book "Optimization for Data Analysis", by Stephen Wright and Benjamin Recht.

Consider the linear least squares problem:

$$\min_{x \in \mathbb{R}^n} f(x) = \frac{1}{2} \|Ax - b\|^2 \tag{1}$$

where $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$.

Assume that m < n and that A has full row rank.

We will note $0 < \lambda_1 \le \lambda_2 \le \cdots \le \lambda_m$ the eigenvalues of the matrix AA^{\top} .

Also, we assume that there exists (at least) one solution z to the linear system Az = b.

<u>Remark:</u> You can use without proof that the nonzero eigenvalues of $A^{\top}A$ are the same as the nonzero eigenvalues of AA^{\top} .

- 1. Characterize the stationary points, local minima and global minima of the optimization problem (1).
- 2. Write down the steepest gradient descent update rule for the optimization problem (1), with the choice of step size $\alpha = \frac{1}{L}$ (you also have to express L explicitly).
- 3. Let x_0, \ldots, x_k be the iterates of the steepest gradient descent method with $x_0 = 0$. Using the results from the lecture, can we derive an inequality of the form:

$$\frac{1}{2} \|Ax_k - b\|^2 \le C\rho^k, \tag{2}$$

for some C > 0 and $\rho \in (0, 1)$?

4. Define $r_k := Ax_k - b$. Show that:

$$r_{k+1} = Mr_k \tag{3}$$

for some symmetric matrix M.

Also, provide the eigenvalues of the matrix M.

5. Conclude that we actually have the inequality:

$$\frac{1}{2} \left\| Ax_k - b \right\|^2 \le C\rho^k \tag{4}$$

for some C > 0 and $\rho \in (0, 1)$.

Exercise 2: Gauss-Southwell method (12 points)

This exercise is inspired from Exercise 4 in Chapter 3 of the book "Optimization for Data Analysis", by Stephen Wright and Benjamin Recht.

The Gauss-Southwell method is the following iterative method:

For $k = 0, 1, 2, \cdots$:

$$x_{k+1,i} = \begin{cases} x_{k,i} - \alpha \nabla f(x_k)_{i_k} & \text{if } i = \arg\max_{j} |\nabla f(x_k)_{j}| \\ x_{k,i} & \text{otherwise} \end{cases}$$
 (5)

where $x_{k,i}$ is the *i*-th component of the vector x_k , and α is a step size.

1. Rewrite the Gauss-Southwell method in the standard form:

For
$$k = 0, 1, 2, \cdots$$
:
$$x_{k+1} = x_k + \alpha \varphi(x_k) \tag{6}$$

where the function φ has to be explicitly given.

2. Prove that the function $\varphi(x)$ verifies the two following inequalities for all $x \in \mathcal{X}$:

$$\|\varphi(x)\| \le \|\nabla f(x)\| \tag{7a}$$

$$-\nabla f(x)^{\top} \varphi(x) \ge \frac{1}{n} \|\nabla f(x)\|^2 \tag{7b}$$

3. Now assume that f is L-smooth. Prove that the iterates of the Gauss-Southwell method satisfy the following inequality:

$$f(x_{k+1}) \le f(x_k) - C(\alpha) \|\nabla f(x_k)\|^2$$
 (8)

where $C(\alpha)$ is a function of α that you have to find.

Hint: Use the following inequality for L-smooth functions:

$$f(y) \le f(x) + \nabla f(x)^{\top} (y - x) + \frac{L}{2} \|y - x\|^2$$

and the inequalities from the previous questions.

- 4. Find the value $\bar{\alpha}$ that minimizes the value of $C(\alpha)$.
- 5. Now assume that f is μ -strongly convex. Proves that the following holds for any x:

$$f(x) - f(x^*) \le \frac{1}{2\mu} \|\nabla f(x)\|^2$$
.

Use this result to prove the following inequality for the iterates of the Gauss-Southwell with $\alpha = \bar{\alpha}$:

$$f(x_k) - f(x^*) \le \rho^k (f(x_0) - f(x^*)),$$
 (9)

where $\rho \in (0,1)$ has to be explicitly found.

6. Conclude regarding the convergence of the method for strongly convex functions (and L-smooth functions).

Exercise 3: L2 Penalization for Almost Convex Functions (10 points)

This exercise is inspired from Exercise 6 in Chapter 3 of the book "Optimization for Data Analysis", by Stephen Wright and Benjamin Recht.

Consider the optimization problem of minimizing a function g(x) that is continuously twice differentiable, but not convex. However, it is *almost convex*, and L-smooth, i.e. the following holds:

$$-\varepsilon I_n \prec \nabla^2 q(x) \prec M I_n \tag{10}$$

where $\varepsilon \geq 0$ is rather small.

Also, assume that a good guess \bar{x} of the solution x^* is available:

$$||x^* - \bar{x}|| \le r \tag{11}$$

for some r > 0.

We choose to apply the gradient descent method to a modified version of the problem:

$$\min_{x \in \mathbb{R}^n} f_{\lambda}(x) = g(x) + \frac{\lambda}{2} \|x - \bar{x}\|^2$$
(12)

where $\lambda \geq 0$ is a regularization parameter.

1. Let x_{λ}^{\star} be the solution of the optimization problem (12). Prove that the following holds for all $x \in \mathbb{R}^n$:

$$g(x) - g(x^*) \le f_{\lambda}(x) - f_{\lambda}(x_{\lambda}^*) + \frac{\lambda r^2}{2}$$
(13)

- 2. Assume that $\lambda > \varepsilon$. Then show that f_{λ} is μ -strongly convex for some $\mu > 0$ that you should specify.
- 3. Write down the steepest gradient descent update rule for the optimization problem (12), with the optimal choice of step size.

<u>Hint:</u> For an L-smooth function; the optimal step size choice is $\alpha = \frac{1}{L}$.

4. Prove, using the results from the lecture, that the following holds:

$$f(x_k) - f(x_\lambda^*) \le C_\lambda \rho_\lambda^k \tag{14}$$

where $\rho_{\lambda} \in (0,1)$ and $C_{\lambda} > 0$ have to be explicitly given.

5. Conclude that for a specific choice of of λ (that you should specify), and $k \ge \bar{k}$ (where \bar{k} is a number that you have to specify), the following holds:

$$q(x_k) - q(x^*) < 2\varepsilon r^2 \tag{15}$$

Programming tasks (4 bonus points)

Open the jupyter notebook programming_exercise3.ipynb, and fill in the missing parts of the code.

If you are struggling with downloading Jupyter notebook, you can also use it online via

https://jupyter.org/try-jupyter/lab.