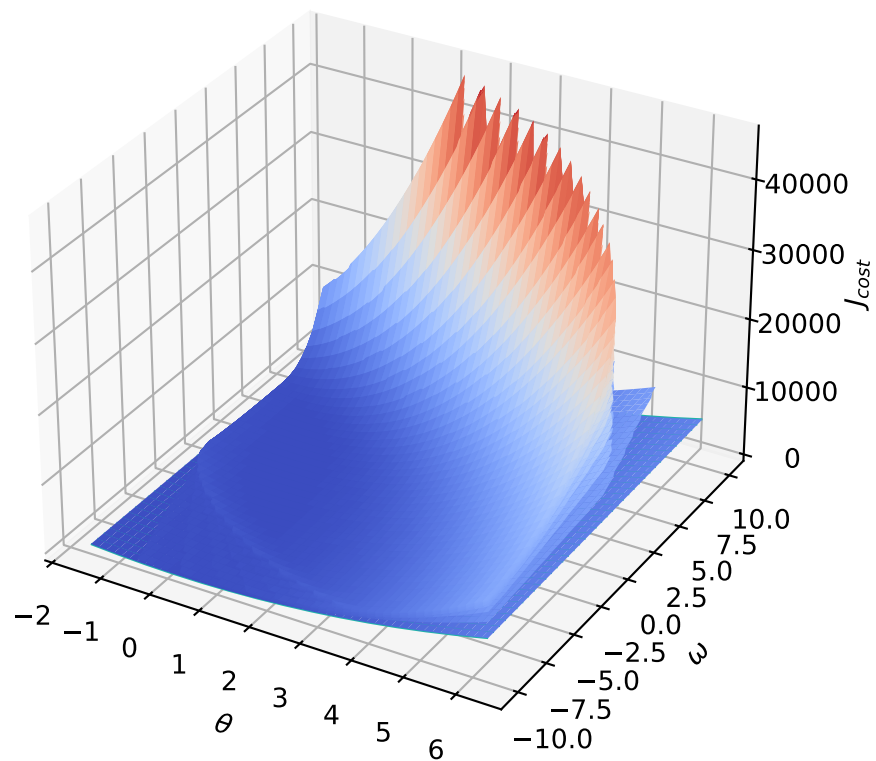


Cost-to-go function



Optimal feedback control

