

Embedded Nonlinear MPC Software

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Different Levels of Optimal Control Software



Algorithmic Ingredients:

- ▶ Basic linear algebra subroutines (BLAS)
- ▶ Algorithmic Differentiation (AD)
- ▶ Numerical Integration
- ▶ Quadratic Programming (QP)

- ▶ Nonlinear Programming (NLP)
- ▶ Nonlinear Optimal Control (NOC)
- ▶ Nonlinear Model Predictive Control (NMPC)
- ▶ Mixed Integer Optimal Control (MIOC)
- ▶ Nonsmooth Optimal Control

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Software:

- ▶ Eigen, BLASFEO, ...
- ▶ ADOL-C, ACADO, CasADI, ...
- ▶ SUNDIALS, DAESOL, ACADO Integrators, ...
- ▶ CPLEX, OOQP, OSQP, qpOASES, qpDUNES, HPIPM, ...
- ▶ KNITRO, SNOPT, IPOPT, ...
- ▶ MUSCOD-II, ACADO, AWEbox, ...
- ▶ AutoGenU, GRAMPC, ACADO Code Generation, acados, ...
- ▶ MS-MINTOC, pycombina, ...
- ▶ NOSNOC, ...

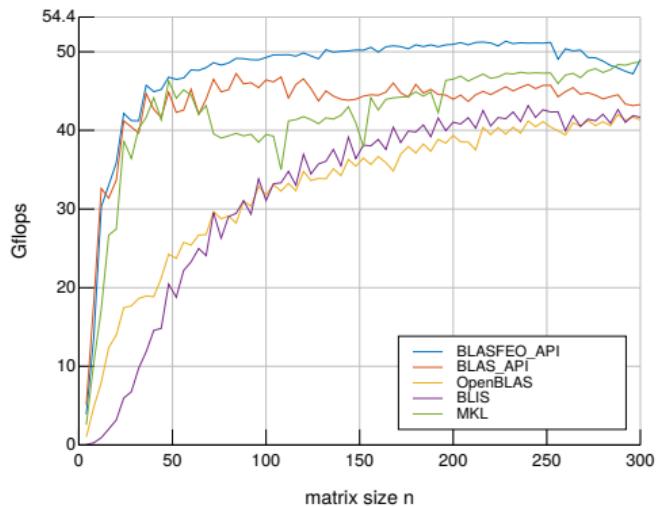
BLASFEO – The Linear Algebra Framework



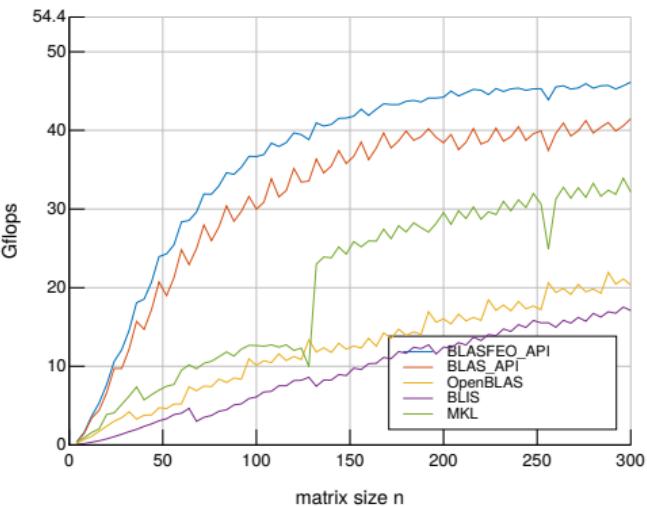
- ▶ Basic Linear Algebra Subroutines For Embedded Optimization
- ▶ open-source¹, permissive BSD-2 license, by Gianluca Frison (MOSEK/Uni Freiburg)
- ▶ aim: provide high-performance linear algebra for embedded optimization applications
 - ▶ optimize performance for dense matrices fitting in cache
 - ▶ special focus on performance for small matrices
 - ▶ coded in C plus explicit vectorization using assembly
 - ▶ optimal register blocking
 - ▶ enhanced cache usage
 - ▶ no code-generation but rather library of routines
- ▶ two interfaces
 - ▶ standard BLAS API
 - ▶ standard column-major matrix format, high-performance for small to large matrices
 - ▶ BLASFEO own API
 - ▶ special panel-major matrix format further enhancing small-scale performance

¹<https://github.com/giaf/blasfeo>

BLASFEO – Selected Benchmarks



(a) dgemm_nt (matrix multiplication)



(b) dpotrf_I (Cholesky factorization)

Figure: Performance of BLASFEO (BLASFEO_API and BLAS_API), OpenBLAS 0.3.4, MKL 2019.1.144 and BLIS 0.5.0 on one core of an Intel Core i7 4810MQ (Haswell architecture).