

## Solution for Exercise 3: Newton's method for optimization

TEMPO Summer School on Numerical Optimal Control and Embedded Optimization  
University of Freiburg, July 27 - August 7, 2015  
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### Part 0: Plotting Rosenbrock's function

```
clc;
clear all;
close all;

% Create figure
figure1 = figure('Position',[1 400 1200 600]);
colormap('gray');
axis square;
R=0:.002:sqrt(2);
TH=2*pi*(0:.002:1);
X=R'*cos(TH);
Y=R'*sin(TH);
Z=log(1+vrosenbrock(X,Y));

% Create subplot
subplot1 = subplot(1,2,1,'Parent',figure1);
view([124 34]);
grid('on');
hold('all');

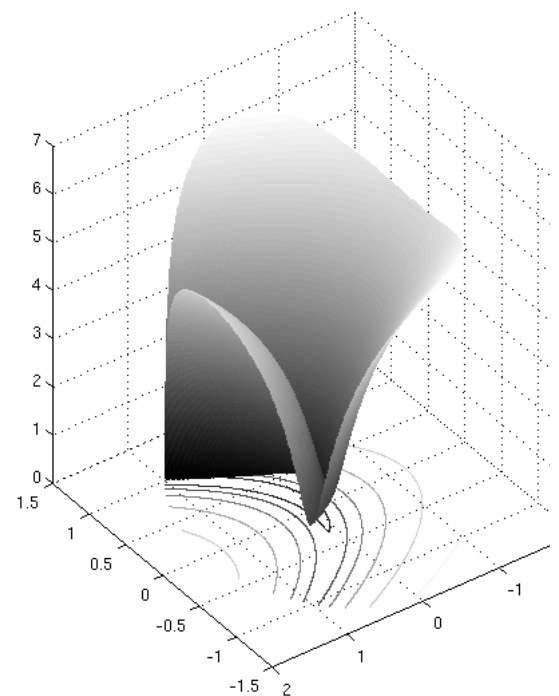
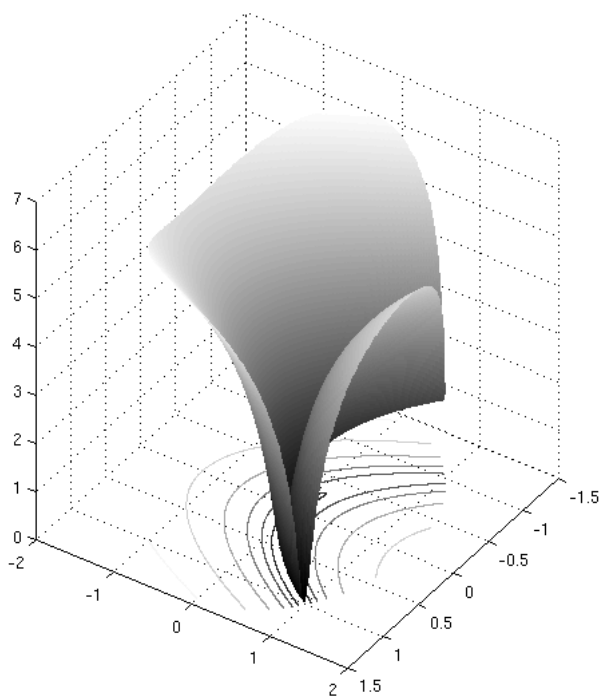
% Create surface
surf(X,Y,Z,'Parent',subplot1,'LineStyle','none');

% Create contour
contour(X,Y,Z,'Parent',subplot1);

% Create subplot
subplot2 = subplot(1,2,2,'Parent',figure1);
view([234 34]);
grid('on');
hold('all');

% Create surface
surf(X,Y,Z,'Parent',subplot2,'LineStyle','none');

% Create contour
contour(X,Y,Z,'Parent',subplot2);
```



## Part 1: Implementing Newton's method

```
z = [0; 0];
res = 1; iter = 0;
while norm(res) > 1e-5
    [-,res,H] = D2f_eval(z);
    dz = -H\res;
    z = z + dz;
    iter = iter+1;
end
disp(['solution found in ' num2str(iter) ' iterations: x = ' num2str(z(1)) ', y = ' num2str(z(2))'])
```

dz =

```
1
0
```

dz =

```
0
1
```

dz =

```
0
0
```

solution found in 3 iterations: x = 1, y = 1

## Part 2: Solving the problem using fminunc

fminunc's solution:

```
options = optimoptions(@fminunc,'Display','iter','Algorithm','quasi-newton');
x_sol = fminunc(@f_eval,[0 0],options)

% fminunc's solution with gradient and hessian:
options = optimoptions(@fminunc,'Display','iter','Algorithm','trust-region','GradObj','on','Hessian','on');
x_sol1 = fminunc(@D2f_eval,[0 0],options)
```

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	3	1		2
1	12	0.771192	0.0817341	5.34
2	15	0.610658	1	6.73
3	18	0.522451	1	7.11
4	24	0.261629	0.7075	1.88
5	30	0.248996	0.5	3.44
6	33	0.207486	1	2.94
7	36	0.125351	1	1.5
8	39	0.0893498	1	3.93
9	42	0.0308666	1	1.23
10	48	0.0200762	0.322023	1.95
11	51	0.0138484	1	1.57
12	54	0.0044155	1	0.303
13	60	0.00268685	0.5	1.14
14	63	0.000276528	1	0.28
15	66	4.2104e-05	1	0.122
16	69	1.37272e-06	1	0.00796
17	72	7.48542e-07	1	0.0303
18	75	3.34562e-09	1	0.00221
19	78	6.71604e-11	1	7.22e-05
				First-order optimality
Iteration	Func-count	f(x)	Step-size	optimality
20	81	1.94742e-11	1	1.06e-06

Local minimum found.

Optimization completed because the size of the gradient is less than the default value of the function tolerance.

x\_sol =

```
1.0000 1.0000
```

Iteration	f(x)	Norm of step	First-order optimality	CG-iterations
0	1		2	
1	1	1	2	1
2	0.953125	0.25	12.5	0
3	0.549578	0.0625	1.63	1
4	0.414158	0.125	2.74	1
5	0.292376	0.218082	5.67	1
6	0.155502	0.123894	0.954	1
7	0.117347	0.25	7.16	1
8	0.0385147	0.093587	0.308	1

9	0.0385147	0.284678	0.308	1
10	0.0268871	0.0625	0.351	0
11	0.0118213	0.125	1.38	1
12	0.00295219	0.113248	0.983	1
13	0.000358228	0.0664421	0.313	1
14	1.04116e-05	0.0322022	0.0759	1
15	1.29552e-08	0.00556519	0.00213	1
16	2.20449e-14	0.00023683	3.59e-06	1

Local minimum possible.

fminunc stopped because the final change in function value relative to its initial value is less than the default value of the function tolerance.

```
x_sol1 =
    1.0000    1.0000
```

## Part 2: Solving the constrained problem using fmincon

```
options = optimoptions(@fmincon,'Display','iter',...
    'Algorithm','interior-point','GradObj','on','GradConstr','on','Hessian','bfgs');
x_sol2 = fmincon(@Df_eval,[0 0],[],[],[],[],[],[],[],@c_eval,options)

options = optimoptions(@fmincon,'Display','iter',...
    'Algorithm','interior-point','GradObj','on','GradConstr','on','Hessian','user-supplied','HessFcn',@hessian_fun);
x_sol3 = fmincon(@Df_eval,[0 0],[],[],[],[],[],[],[],@c_eval,options)
```

Iter	F-count	f(x)	Feasibility	First-order optimality	Norm of step
0	1	1.000000e+00	0.000e+00	2.000e+00	
1	9	7.753529e-01	0.000e+00	6.250e+00	1.768e-01
2	12	6.519631e-01	0.000e+00	9.048e+00	1.679e-01
3	13	5.543204e-01	0.000e+00	8.033e+00	1.203e-01
4	14	2.985193e-01	0.000e+00	1.790e+00	9.329e-02
5	15	2.653787e-01	0.000e+00	2.788e+00	5.723e-02
6	16	1.897171e-01	0.000e+00	2.311e+00	1.147e-01
7	17	1.513684e-01	0.000e+00	9.707e-01	5.764e-02
8	18	1.153323e-01	0.000e+00	1.127e+00	8.168e-02
9	19	1.198046e-01	0.000e+00	1.000e-01	1.521e-02
10	20	8.909926e-02	0.000e+00	8.379e-01	8.301e-02
11	21	6.771924e-02	0.000e+00	1.365e+00	7.148e-02
12	22	6.437627e-02	0.000e+00	1.147e-01	5.702e-03
13	23	6.329018e-02	0.000e+00	1.883e-02	3.773e-03
14	24	5.161965e-02	0.000e+00	3.016e-01	4.464e-02
15	25	4.964186e-02	0.000e+00	7.915e-02	7.896e-03
16	26	4.955399e-02	0.000e+00	5.465e-03	4.184e-04
17	27	4.954834e-02	0.000e+00	3.993e-03	2.209e-05
18	28	4.658288e-02	0.000e+00	1.318e-02	1.255e-02
19	29	4.647010e-02	0.000e+00	8.006e-04	4.940e-04
20	30	4.569141e-02	0.000e+00	3.136e-03	3.379e-03
21	31	4.568281e-02	0.000e+00	6.437e-05	3.974e-05
22	32	4.568281e-02	0.000e+00	8.000e-06	1.083e-07
23	33	4.567641e-02	0.000e+00	1.601e-06	2.793e-05
24	34	4.567482e-02	0.000e+00	2.162e-08	6.916e-06

Local minimum found that satisfies the constraints.

Optimization completed because the objective function is non-decreasing in feasible directions, to within the default value of the function tolerance, and constraints are satisfied to within the default value of the constraint tolerance.

```
x_sol2 =
    0.7864    0.6177
```

Iter	F-count	f(x)	Feasibility	First-order optimality	Norm of step
0	1	1.000000e+00	0.000e+00	2.000e+00	
1	4	8.639096e-01	0.000e+00	1.033e+01	2.273e-01
2	5	5.025640e-01	0.000e+00	8.470e-01	1.041e-01
3	7	3.812427e-01	0.000e+00	5.829e+00	1.915e-01
4	8	2.320844e-01	0.000e+00	8.002e-01	1.076e-01
5	10	1.582944e-01	0.000e+00	5.122e+00	2.085e-01
6	11	1.133520e-01	0.000e+00	9.882e-02	2.079e-02
7	12	7.723643e-02	0.000e+00	1.135e+00	1.048e-01
8	13	6.519418e-02	0.000e+00	7.045e-02	3.596e-02
9	14	6.317567e-02	0.000e+00	1.915e-02	7.195e-03
10	15	5.136832e-02	0.000e+00	1.909e-01	4.508e-02
11	16	4.958223e-02	0.000e+00	4.027e-03	7.310e-03
12	17	4.590562e-02	0.000e+00	2.208e-02	1.562e-02
13	18	4.571511e-02	0.000e+00	4.281e-05	8.422e-04
14	19	4.571479e-02	0.000e+00	4.000e-05	1.392e-06
15	20	4.568282e-02	0.000e+00	8.015e-06	1.395e-04
16	21	4.567489e-02	0.000e+00	1.070e-07	3.463e-05

Local minimum found that satisfies the constraints.

Optimization completed because the objective function is non-decreasing in feasible directions, to within the default value of the function tolerance, and constraints are satisfied to within the default value of the constraint tolerance.

x\_sol3 =

0.7864 0.6177