Two-Stage Robust Integer Programming

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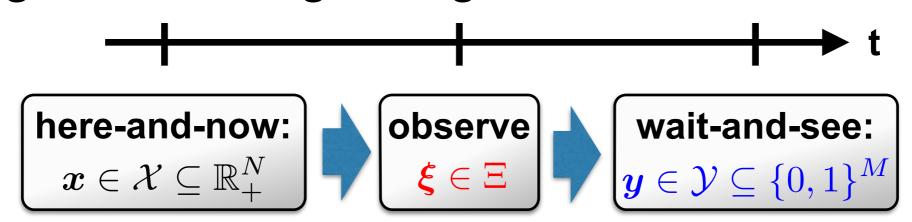
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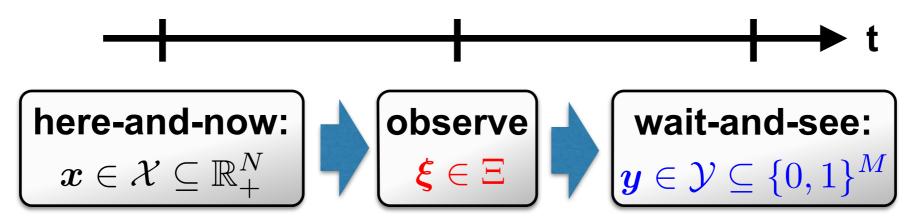
Two-Stage Robust Integer Programs

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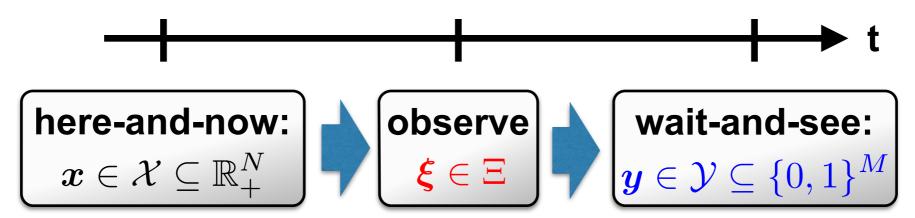
Two-Stage Robust Integer Program:



Mathematical Formulation:

Two-Stage Robust Integer Programs

Two-Stage Robust Integer Program:



Mathematical Formulation:

$$\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^\top \boldsymbol{C} \, \boldsymbol{x} + \min_{\boldsymbol{y} \in \mathcal{Y}} \left\{ \boldsymbol{\xi}^\top \boldsymbol{Q} \, \boldsymbol{y} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X} \end{array}$$

Applications:



operations mgmt.



investment planning

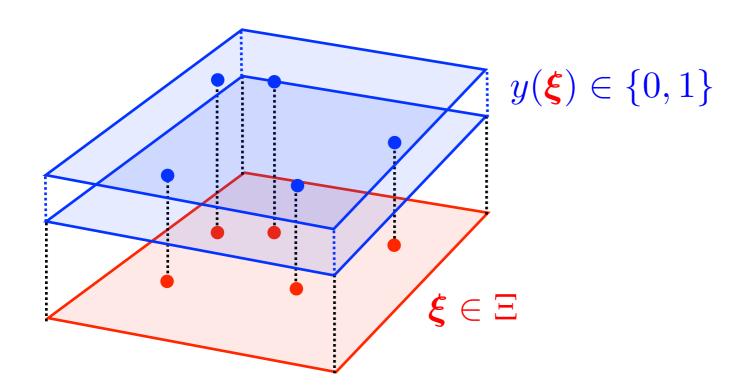


game theory

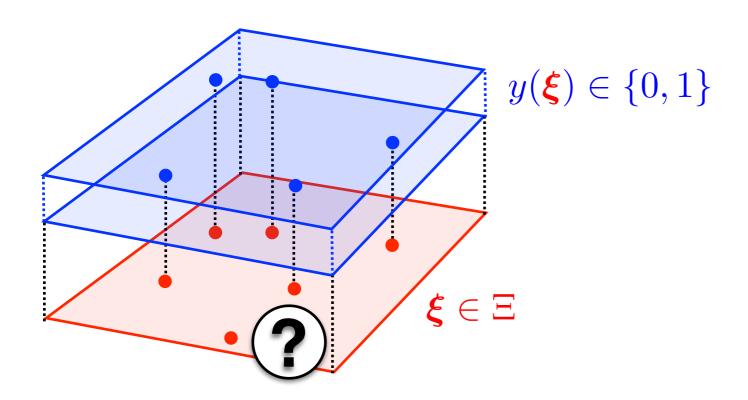
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1 Exact Approaches: not available

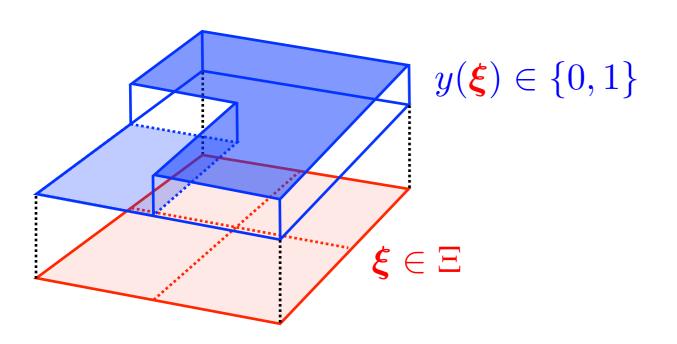
- 1 Exact Approaches: not available
- 2 Sampling-Based Approximations:



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- 2 Sampling-Based Approximations: progressive approximation



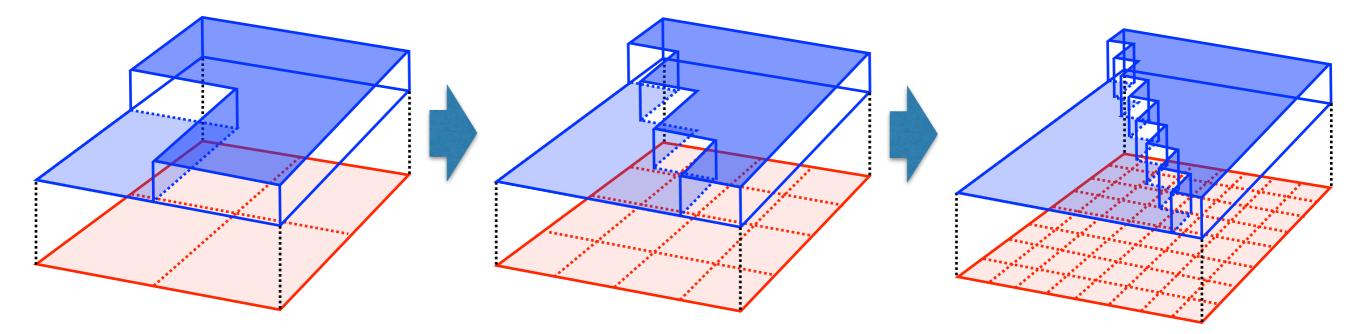
- 1 Exact Approaches: not available
- 2 Sampling-Based Approximations: progressive approximation
- **3** Space-Partitioning Approximations:



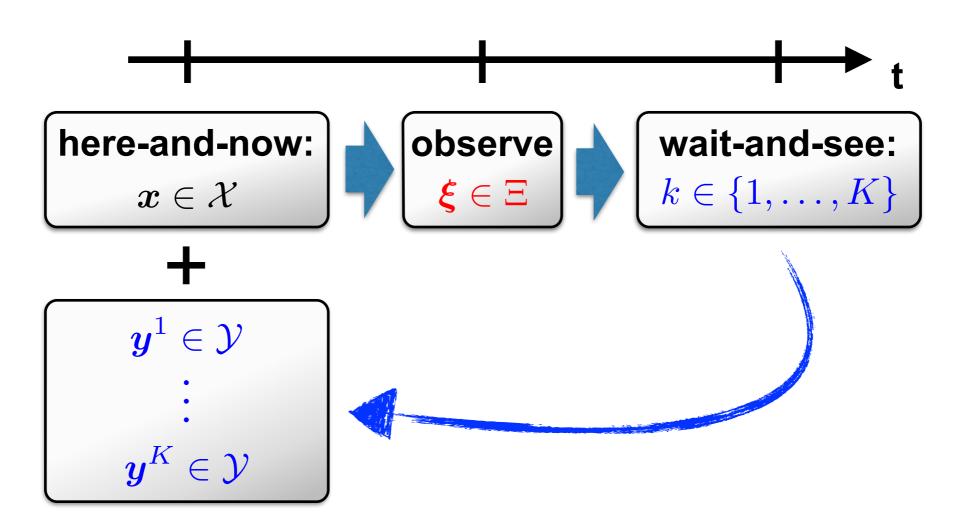
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\begin{array}{|c|c|c|c|c|}\hline \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[ \boldsymbol{\xi}^\top \boldsymbol{C} \, \boldsymbol{x} + \min_{\boldsymbol{y} \in \mathcal{Y}} \left\{ \boldsymbol{\xi}^\top \boldsymbol{Q} \, \boldsymbol{y} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X} \end{array}
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- 1 Exact Approaches: not available
- 2 Sampling-Based Approximations: progressive approximation
- 3 Space-Partitioning Approximations: exponential growth

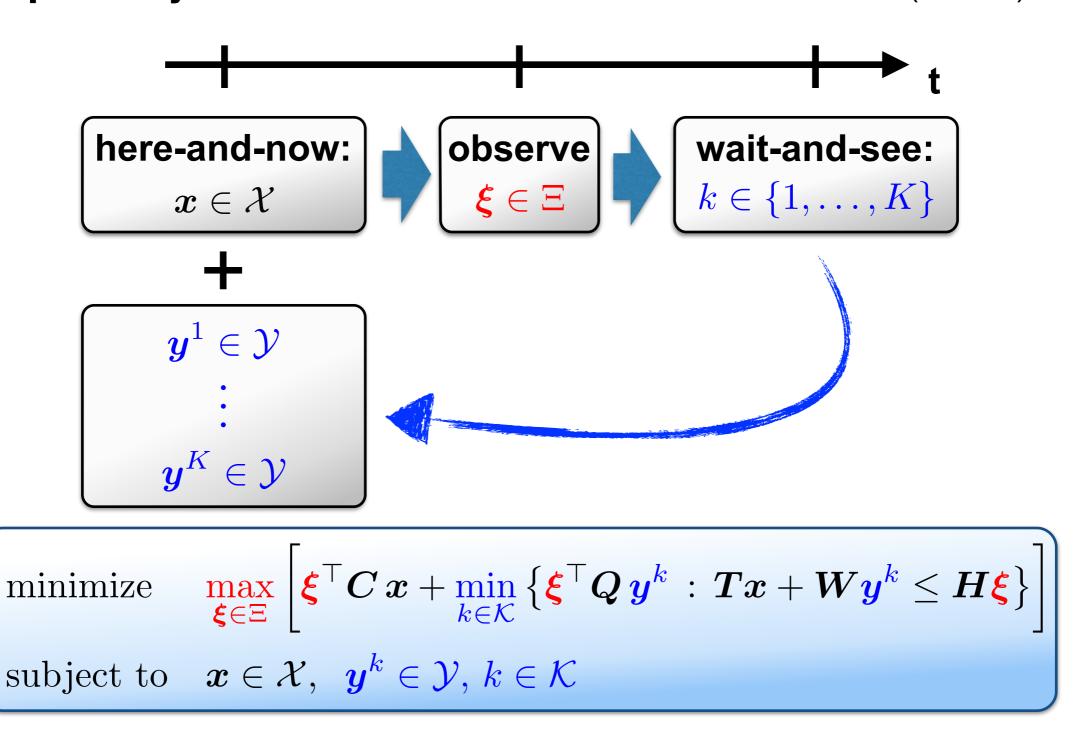
$$\max_{\xi \in [0,1]^2} \min_{y \in \{0,1\}} \left\{ y - \xi_1 - \xi_2 : y \ge \xi_1 + \xi_2 - 1 \right\}$$



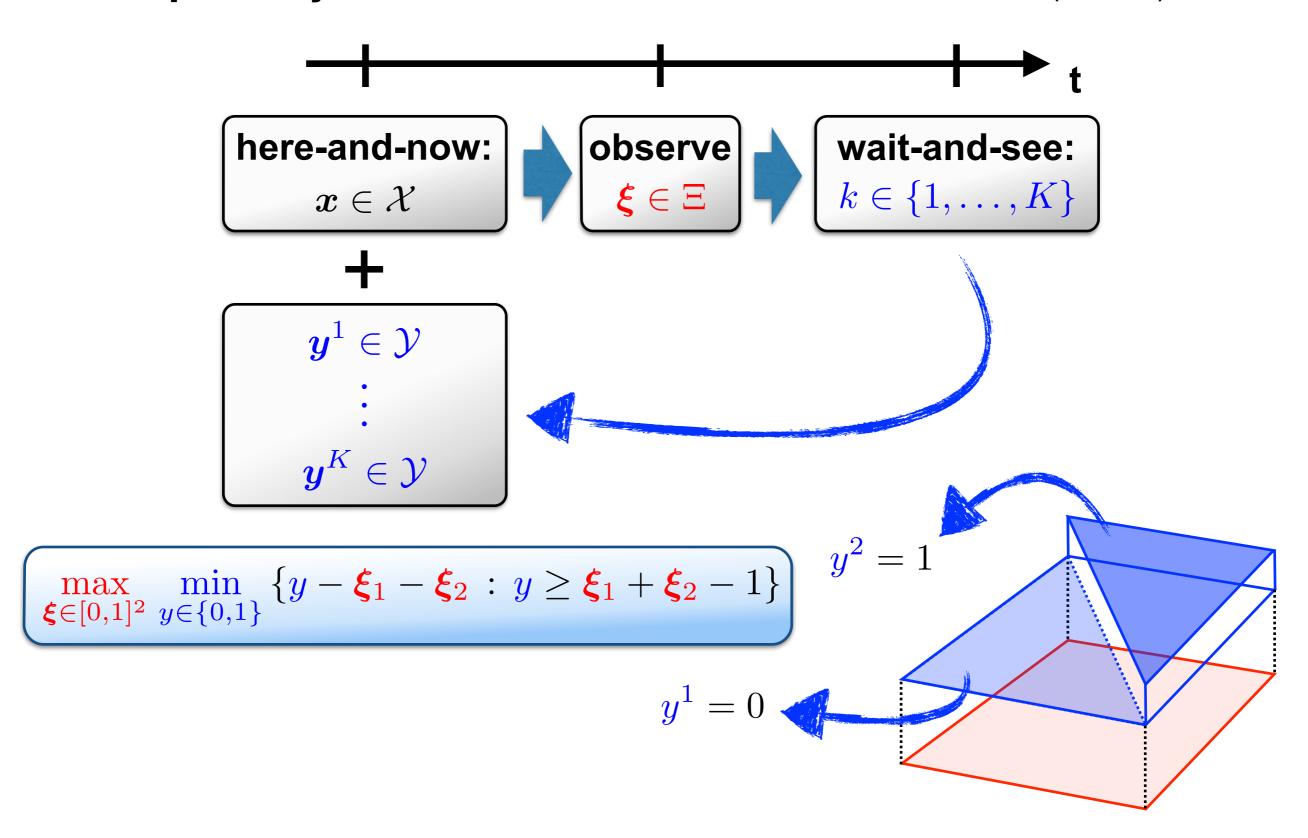
K-Adaptability Problem: Bertsimas and Caramanis (2010)



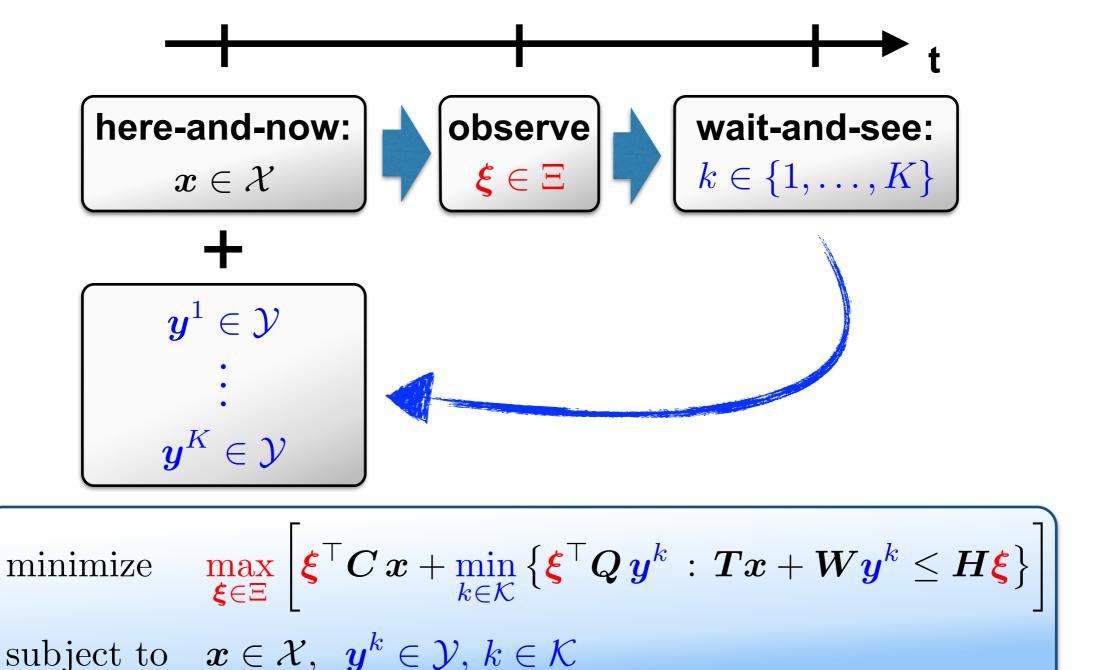
K-Adaptability Problem: Bertsimas and Caramanis (2010)



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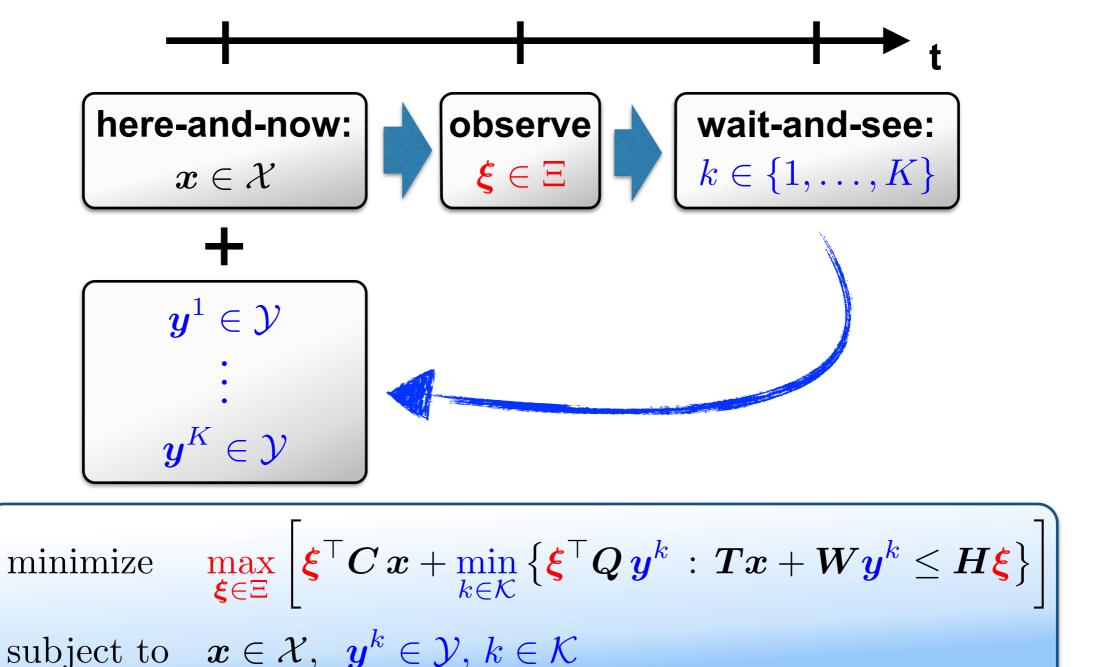


K-Adaptability Problem: Bertsimas and Caramanis (2010)



How good is the approximation?

K-Adaptability Problem: Bertsimas and Caramanis (2010)



How good is the approximation, and can we solve it?

The *K*-Adaptability Problem:

Objective Uncertainty

The K-Adaptability Problem with Objective Uncertainty:

Objective Uncertainty

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$$\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \, k \in \mathcal{K} \end{array}$$

How good is the approximation?

The K-Adaptability Problem with Objective Uncertainty:

$$\begin{array}{|c|c|c|c|c|c|}\hline \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \, k \in \mathcal{K} \end{array}$$

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Theorem (Objective Uncertainty): The K-Adaptability Problem attains the same objective value as the Two-Stage Robust Integer Program whenever $K \ge \min\{\dim \mathcal{Y}, \dim \Xi\} + 1$.

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Consider the \overline{K} -Adaptability Problem with $\overline{K} = \{1, \dots, \overline{K} = |\mathcal{Y}|\}$:

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \overline{\mathcal{K}}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right]$$
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where $\Delta_{\overline{K}}$ denotes the unit simplex in $\mathbb{R}^{\overline{K}}$.

 \overline{K} -Adaptability Problem

Theorem (Objective Uncertainty): The K-Adaptability Problem attains the same objective value as the Two-Stage Robust Integer Program whenever $K \ge \min\{\dim \mathcal{Y}, \dim \Xi\} + 1$.

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subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \overline{\mathcal{K}}$

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Use Minimax Theorem to exchange order of max and min:

minimize
$$\min_{\boldsymbol{\lambda} \in \Delta_{\overline{K}}} \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \sum_{k \in \overline{\mathcal{K}}} \boldsymbol{\lambda}_{k} \cdot \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \ k \in \overline{\mathcal{K}}$

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Combine minimization problems:

$$\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \sum_{k \in \overline{\mathcal{K}}} \boldsymbol{\lambda}_k \cdot \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^k \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \, k \in \overline{\mathcal{K}}, \\ \boldsymbol{\lambda} \in \Delta_{\overline{\mathcal{K}}} \end{array}$$

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Reformulate objective function:

$$\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} \boldsymbol{Q} \cdot \sum_{k \in \overline{\mathcal{K}}} \boldsymbol{\lambda}_k \boldsymbol{y}^k \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \overline{\mathcal{K}}, \\ & \boldsymbol{\lambda} \in \Delta_{\overline{K}} \end{array}$$

Theorem (Objective Uncertainty): The K-Adaptability Problem attains the same objective value as the Two-Stage Robust Integer Program whenever $K \ge \min\{\dim \mathcal{Y}, \dim \Xi\} + 1$.

Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Apply Carathéodory's Theorem:

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \begin{bmatrix} \boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} \boldsymbol{Q} & \sum_{k \in \overline{\mathcal{K}}} \boldsymbol{\lambda}_k \boldsymbol{y}^k \end{bmatrix}$$
 subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \overline{\mathcal{K}},$ $\boldsymbol{\lambda} \in \Delta_{\overline{K}}$ \boldsymbol{y}^9 \boldsymbol{y}^1 \boldsymbol{y}^2 \boldsymbol{y}^3 \boldsymbol{y}^4 \boldsymbol{y}^6 \boldsymbol{y}^5

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 subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \boldsymbol{k} \in \mathcal{K},$ $\boldsymbol{\lambda} \in \Delta_{\boldsymbol{K}}$

where $\mathcal{K} = \{1, \dots, K = \dim \mathcal{Y} + 1\}$.

Theorem (Objective Uncertainty): The K-Adaptability Problem attains the same objective value as the Two-Stage Robust Integer Program whenever $K \ge \min\{\dim \mathcal{Y}, \dim \Xi\} + 1$.

Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Separate the two minimizations:

minimize
$$\min_{\boldsymbol{\lambda} \in \Delta_K} \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^\top \boldsymbol{C} \, \boldsymbol{x} + \sum_{k \in \mathcal{K}} \boldsymbol{\lambda}_k \cdot \boldsymbol{\xi}^\top \boldsymbol{Q} \, \boldsymbol{y}^k \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \mathcal{K}$

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

Use Minimax Theorem to exchange order of min and max:

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{\boldsymbol{\lambda} \in \Delta_K} \sum_{k \in \mathcal{K}} \boldsymbol{\lambda}_k \cdot \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^k \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \mathcal{K}$

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Proof Outline: for $K \ge \dim \mathcal{Y} + 1$

We recover the *K*-Adaptability Problem:

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \ k \in \mathcal{K}$

The K-Adaptability Problem with Objective Uncertainty:

$$\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \, k \in \mathcal{K} \end{array}$$

Can we solve the approximation?

The K-Adaptability Problem with Objective Uncertainty:

Can we solve the approximation?

Theorem (Objective Uncertainty): The *K*-Adaptability Problem has equivalent MILP reformulation whose size scales *polynomially* in the problem data.

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Proof Outline:

Consider the K-Adaptability Problem:

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \ \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \ k \in \mathcal{K}$

Theorem (Objective Uncertainty): The *K*-Adaptability Problem has equivalent MILP reformulation whose size scales *polynomially* in the problem data.

Proof Outline:

Epigraph reformulation of inner min:

minimize
$$\max_{\substack{\boldsymbol{\xi} \in \Xi, \\ \tau \in \mathbb{R}}} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \boldsymbol{\tau} \, : \, \boldsymbol{\tau} \leq \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \; \forall k \in \mathcal{K} \right]$$
subject to $\boldsymbol{x} \in \mathcal{X}, \; \boldsymbol{y}^{k} \in \mathcal{Y}, \; \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{h}, \, k \in \mathcal{K}$



Objective Uncertainty: Tractability

Theorem (Objective Uncertainty): The *K*-Adaptability Problem has equivalent MILP reformulation whose size scales *polynomially* in the problem data.

Proof Outline:

Strong LP duality:

minimize
$$\min_{\substack{\boldsymbol{\alpha} \in \mathbb{R}_+^K, \\ \boldsymbol{\beta} \in \mathbb{R}_+^K}} \left[\boldsymbol{b}^\top \boldsymbol{\alpha} : \boldsymbol{A}^\top \boldsymbol{\alpha} = \boldsymbol{C} \boldsymbol{x} + \sum_{k \in \mathcal{K}} \boldsymbol{\beta}_k \boldsymbol{Q} \boldsymbol{y}^k, \quad \mathbf{e}^\top \boldsymbol{\beta} = 1 \right]$$
 subject to $\boldsymbol{x} \in \mathcal{X}, \quad \boldsymbol{y}^k \in \mathcal{Y}, \quad \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{h}, \quad k \in \mathcal{K}$

Objective Uncertainty: Tractability

Theorem (Objective Uncertainty): The *K*-Adaptability Problem has equivalent MILP reformulation whose size scales *polynomially* in the problem data.

Proof Outline:

Strong LP duality:

minimize
$$\boldsymbol{b}^{\top}\boldsymbol{\alpha}$$

subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ \boldsymbol{T}\boldsymbol{x} + \boldsymbol{W}\boldsymbol{y}^k \leq \boldsymbol{h}, \ k \in \mathcal{K}$
 $\boldsymbol{\alpha} \in \mathbb{R}_+^R, \ \boldsymbol{\beta} \in \mathbb{R}_+^K, \ \boldsymbol{A}^{\top}\boldsymbol{\alpha} = \boldsymbol{C}\boldsymbol{x} + \sum_{k \in \mathcal{K}} \boldsymbol{\beta}_k \boldsymbol{Q}\boldsymbol{y}^k, \ \mathbf{e}^{\top}\boldsymbol{\beta} = 1$

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Linearize bilinear terms: via auxiliary variables $z^k \in \mathbb{R}_+^M, k \in \mathcal{K}$

$$z^k = \beta_k y^k \iff z^k \le y^k, \ z^k \le \beta_k e, \ z^k \ge (\beta_k - 1)e + y^k$$

Epigraph Reformulation

Dualize Inner Problem

Exact Linearization

Summary

The *K*-Adaptability Problem:

Objective Uncertainty:

- * *strong* approximation guarantees
- MILP reformulation that scales polynomially

Constraint Uncertainty

The K-Adaptability Problem with Constraint Uncertainty:

Constraint Uncertainty: Approximation Quality

The K-Adaptability Problem with Constraint Uncertainty:

$$\left[\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \;\; \boldsymbol{y}^{k} \in \mathcal{Y}, \, k \in \mathcal{K} \end{array} \right]$$

How good is the approximation?

Constraint Uncertainty: Approximation Quality

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How good is the approximation?

Theorem (Constraint Uncertainty): The K-Adaptability Problem can attain a *strictly larger objective value* than the Two-Stage Robust Integer Program whenever $K < |\mathcal{Y}|$.

The K-Adaptability Problem with Constraint Uncertainty:

$$\left[\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \, k \in \mathcal{K} \end{array} \right]$$

Can we solve the approximation?

The K-Adaptability Problem with Constraint Uncertainty:

$$\left[\begin{array}{ll} \text{minimize} & \max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \mathcal{K}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right] \\ \text{subject to} & \boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^{k} \in \mathcal{Y}, \, k \in \mathcal{K} \end{array} \right]$$

Can we solve the approximation?

Theorem (Constraint Uncertainty): The K-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies K (but *polynomially* in other problem data).

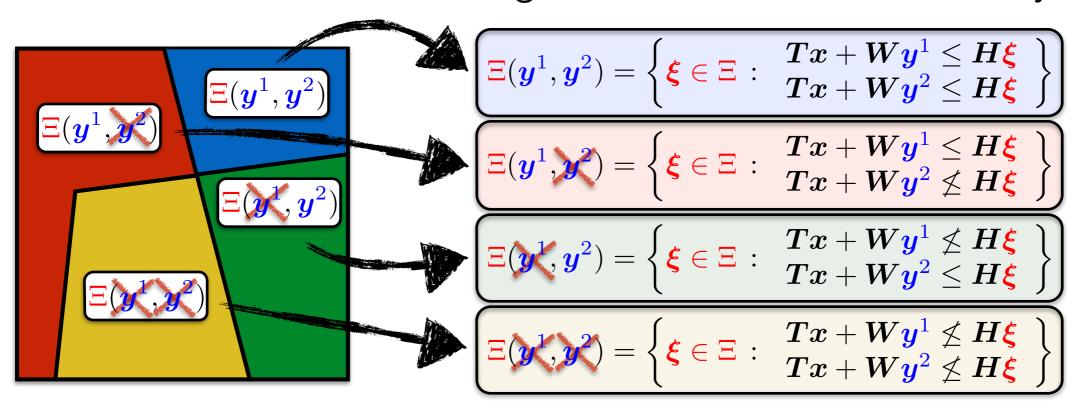
Theorem (Constraint Uncertainty): The *K*-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies *K* (but *polynomially* in other problem data).

Proof Outline: Consider the 2-Adaptability Problem:

Theorem (Constraint Uncertainty): The K-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies K (but *polynomially* in other problem data).

minimize
$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^\top \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^\top \boldsymbol{Q} \, \boldsymbol{y}^k : \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^k \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right]$$
 subject to $\boldsymbol{x} \in \mathcal{X}, \ \boldsymbol{y}^k \in \mathcal{Y}, \ k \in \{1,2\}$

Theorem (Constraint Uncertainty): The *K*-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies *K* (but *polynomially* in other problem data).



$$\Xi = \Xi(\boldsymbol{y}^1, \boldsymbol{y}^2) \cup \Xi(\boldsymbol{y}^1, \boldsymbol{y}^2) \cup \Xi(\boldsymbol{y}^1, \boldsymbol{y}^2) \cup \Xi(\boldsymbol{y}^1, \boldsymbol{y}^2)$$

Theorem (Constraint Uncertainty): The *K*-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies *K* (but *polynomially* in other problem data).

$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right]$$

$$= \max \left\{ \begin{array}{l} \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \end{array}$$

Theorem (Constraint Uncertainty): The K-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies K (but *polynomially* in other problem data).

$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right]$$

$$= \max \left\{ \begin{array}{c} \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \end{array}$$

Theorem (Constraint Uncertainty): The K-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies K (but *polynomially* in other problem data).

$$\max_{\boldsymbol{\xi} \in \Xi} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right]$$

$$= \max \left\{ \begin{bmatrix} \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{k} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{1} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right],$$

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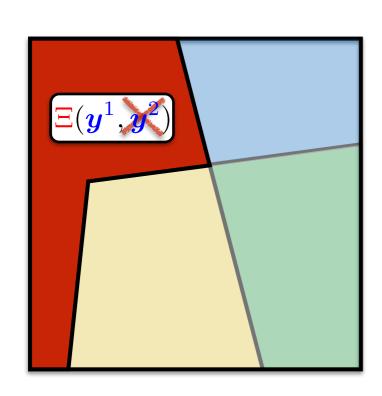
$$= \max \left\{ \begin{bmatrix} \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{k})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{1} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{2} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} \boldsymbol{C} \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} \boldsymbol{Q} \, \boldsymbol{y}^{k} \, : \, \boldsymbol{T} \boldsymbol{x} + \boldsymbol{W} \boldsymbol{y}^{k} \leq \boldsymbol{H} \boldsymbol{\xi} \right\} \right],$$

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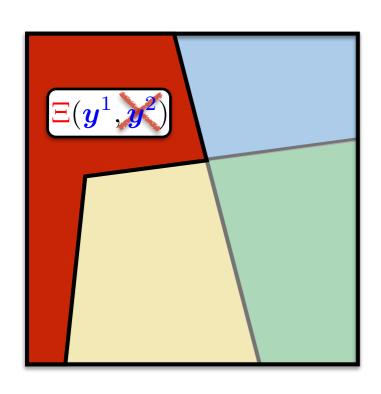
$$= \max \left\{ \begin{bmatrix} \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \min_{k \in \{1,2\}} \left\{ \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{k} \right\} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{1} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\xi}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \max_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \sum_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \sum_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \sum_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \sum_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right], \\ \sum_{\boldsymbol{\xi} \in \Xi(\boldsymbol{y}^{1}, \boldsymbol{y}^{2})} \left[\boldsymbol{\xi}^{\top} C \, \boldsymbol{x} + \boldsymbol{\zeta}^{\top} Q \, \boldsymbol{y}^{2} \right],$$

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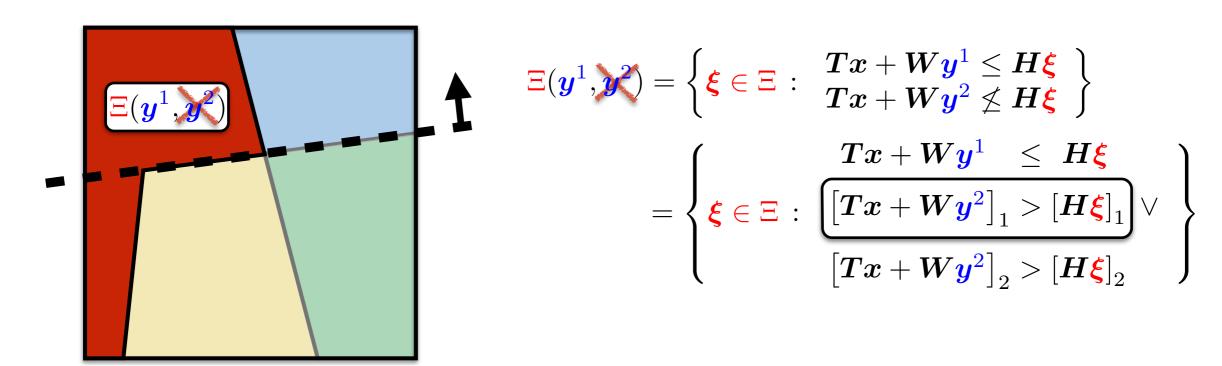
$$oxed{\Xi(oldsymbol{y}^1,oldsymbol{y}^2)} = egin{cases} oldsymbol{\xi} \in \Xi : & oldsymbol{T}oldsymbol{x} + oldsymbol{W}oldsymbol{y}^1 \leq oldsymbol{H}oldsymbol{\xi} \ oldsymbol{T}oldsymbol{x} + oldsymbol{W}oldsymbol{y}^2
ot \leq oldsymbol{H}oldsymbol{\xi} \end{cases}$$

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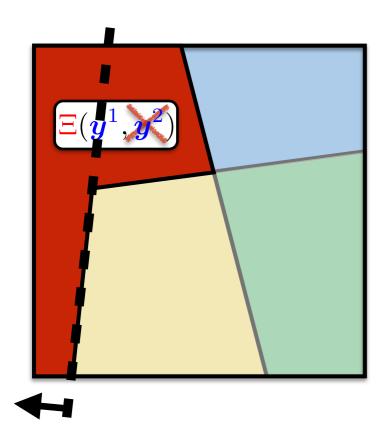


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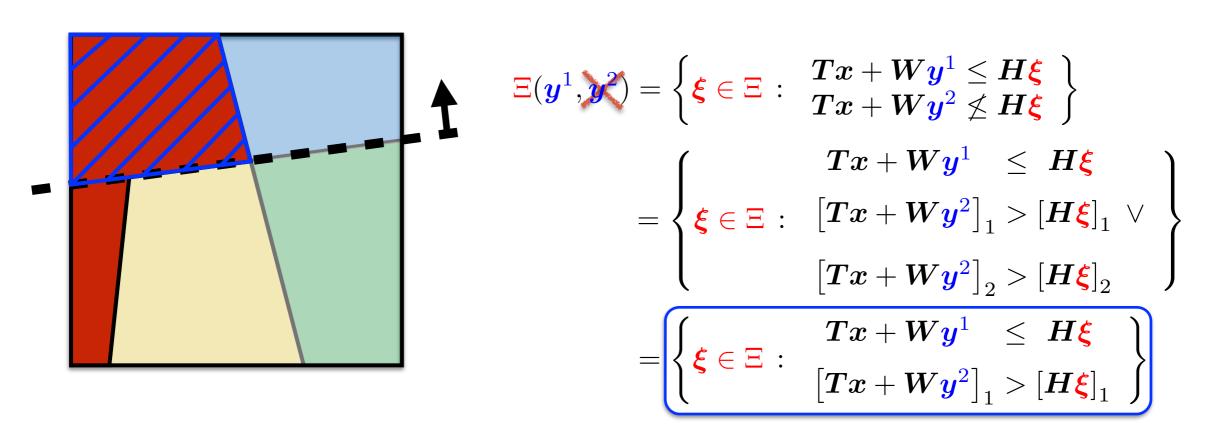


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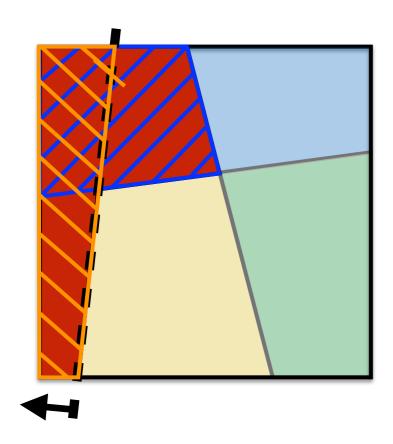


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Theorem (Constraint Uncertainty): The *K*-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies *K* (but *polynomially* in other problem data).



Theorem (Constraint Uncertainty): The *K*-Adaptability Problem has an equivalent MILP reformulation that scales *exponentially* in the number of policies *K* (but *polynomially* in other problem data).



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Summary

The *K*-Adaptability Problem:

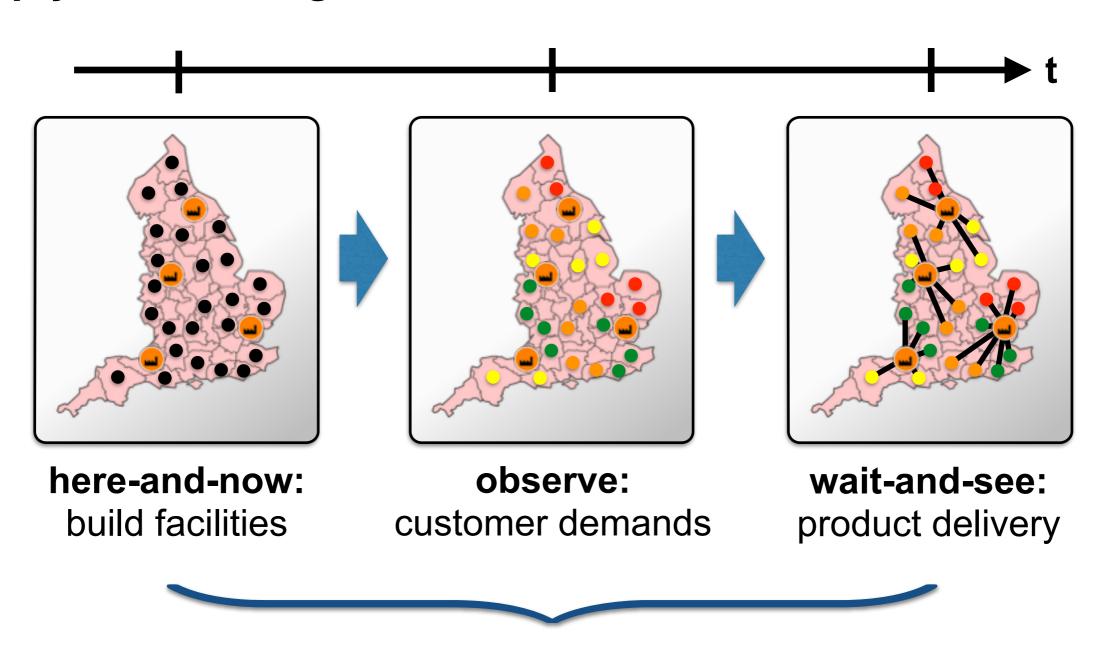
Objective Uncertainty:

- strong approximation guarantees
- MILP reformulation that scales polynomially

Constraint Uncertainty:

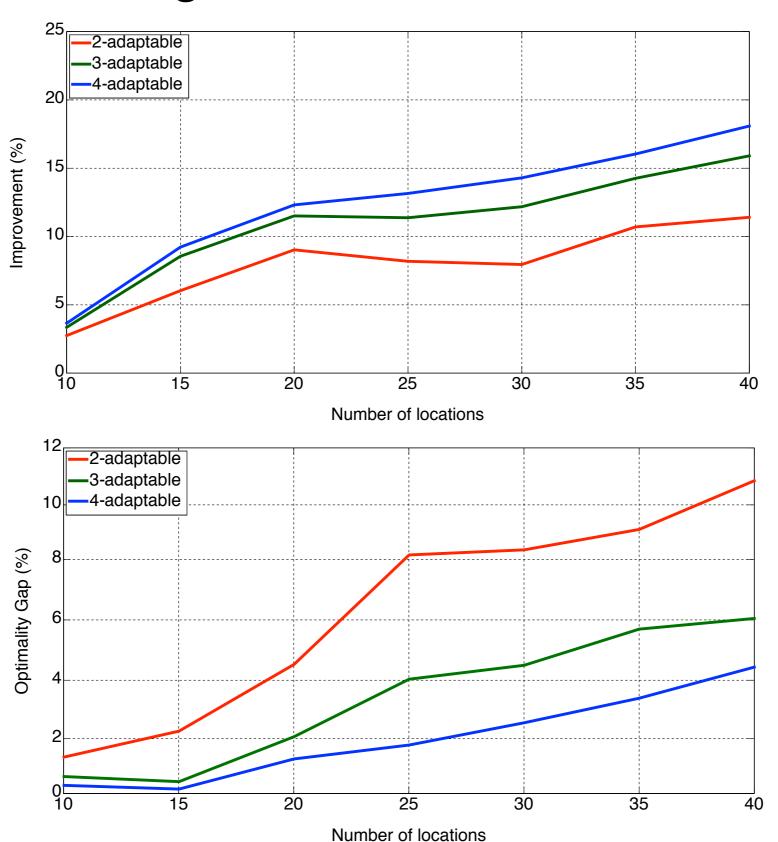
- weak approximation guarantees
- MILP reformulation that scales
 - exponentially in K
 - polynomially in rest

Supply Chain Design:



Can be modeled as two-stage robust integer program with objective uncertainty!

Supply Chain Design:



Investment Planning:



observe:

risk factors

here-and-now: early-stage investment (first mover advantage)

wait-and-see: late-stage investment (no advantage)

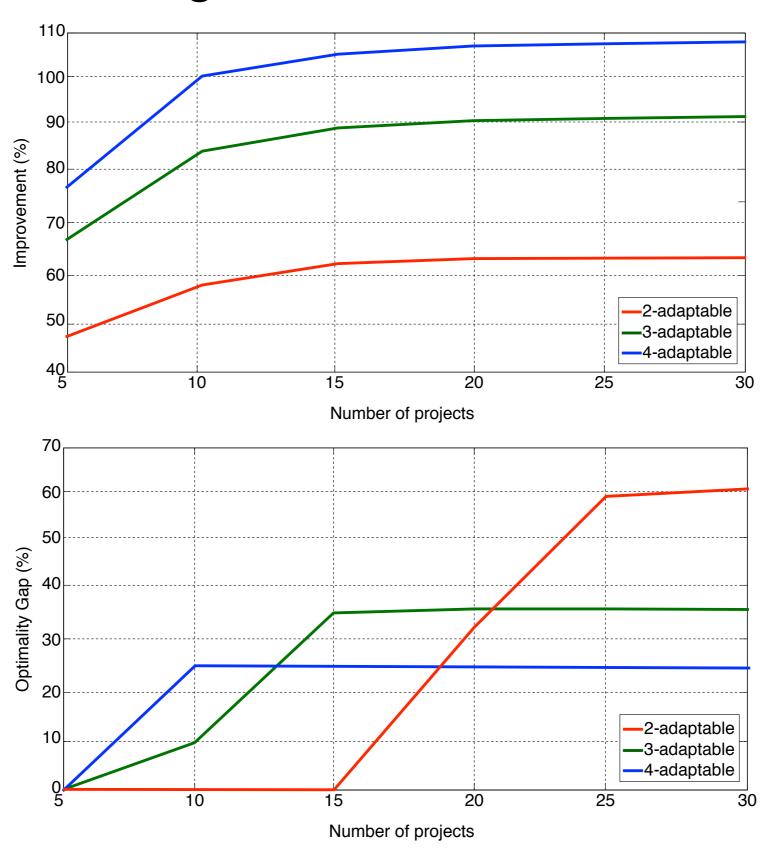
 $\frac{\mathsf{costs:}}{\mathsf{profits:}} \ \ \boldsymbol{c(\boldsymbol{\xi})}^{\top} \boldsymbol{x}$

 $\underline{\mathsf{costs:}} \quad \boldsymbol{c}(\boldsymbol{\xi})^{\top} \boldsymbol{y}(\boldsymbol{\xi})$

profits: $0.8 \cdot \boldsymbol{r}(\boldsymbol{\xi})^{\top} \boldsymbol{y}(\boldsymbol{\xi})$

Can be modeled as two-stage robust integer program with constraint uncertainty!

Investment Planning:



References

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